Not for unauthorized commercial use

BICYCLE/ROWING TYPE ERGOMETER& CONTROLLERS

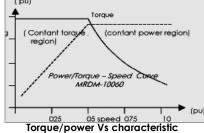
[A.C.TRANSIENT DYNAMOMETER-GRID INTERACTIVE BASED]

Introduction:

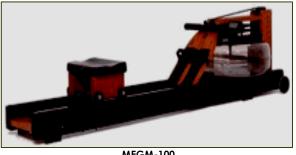
MEGM series of ergometers controllers are available in more than 25 routine models apart from occasional special requirement., virtually offering solutions to various applications like biomedical diagnostic, defense psychological studies, physiotherapy, sport fitness assessment, water sports exercise machines, and many other research & development applications. Ergometer controllers are cascade type feed back type control system and control the torque/power. These Ergometer displays principal parameter like power, rpm and torque as well as other inferential parameter like power/torque capacity, overload power/torque capacity, efficiency, plotting torque/speed and power/speed curve, desired phase trajectories on line. These fast responding ergometer posses least mechanical time constant, windage losses, least rheological problem, mechanical black-lash/ dead band, and exhibits a repeatable and hysteresis less Torque/Power Vs Excitation current characteristics which guarantees accurate identification of parameters during steady state/transient conditions with high degree of stability and resolution. These ergometers are compact and, dynamically balanced & vibration-less motion, inherent self-braking action and thus less hunting with maximum torque/k.watts.

Operating Principle:

In ergometers, a special metal drag cup rotor rotate under the influence of time invariant magnetic field or a magnetic field rotor rotates inside a cup type special metal stator (driver). In either case, the magnetic field intensity is controlled by a high frequency magnetic field feedback controlled chopper, which ensures a time invariant ripple free magnetic field. Rotor rotating under the influence magnetic field cuts the magnetic flux, by virtue of which there develops in it. This brake system may operate in constant power or torque mode. Power absorbed by ergometers and its Torque loading is as under....



 $P = 0.438I_f^2 xN^2$ and $T = 0.438I_f^2 xN$







MEG/M-100			IV IV		WEGW-003	
ELECTRICAL SPE	CIFICATIONs OF ERG	GOMETERS			Power range<100.0 K.Watts	
Model	Power- range watts	R.P.M. X100	Torque n.m.	Volts AC	Amps AC	Tmax ⁰C
MEGM-001	1000.0	30/15	3.1/62	220/440	2.0	60
MEGM-003	3000.0	30/15	9.3/46	220/440	4.0	60
MEGM-005	5000.0	15/09	31.8/53.0	220/440	6.0	70
MEGM-010	10000.0	15/09	63.6/106.0	220/440	10.0	70
MEGM-020	20000.0	09/03	127.2/381.6	220/440	15.0	60
MEGM-030	30000.0	09/03	190.8/574.4	220/440	20.0	60
MEGM-050	50000.0	09/03	318.0/954.0	220/440	30.0	70
MEGM-100	100000.0	09/03	1075.2/3225.7	220/440	50.0	70

ERGOMETERS CONTROLLERS SPECIFICATION:

MEGM010

MEGM020

MEGM030

12X10X10

12X10X10

12X10X10

Operating voltage		220 volts/110/48 volts A.C.						
Chopping frequency		50/400/1000 Hz (option)						
Excitation	0.0-2	00.0 amps(max)						
Regulation		better than 0.5 % of set speed						
Accuracy		99.5% of set point						
Repeatability		100 percent						
Response time		0.05–10.0 sec with soft start						
Interface Signal		0.0-12.0 volts D.C. (proportional to torque)						
Step down ratio		1:50(1:100)						
Control option		constant torque/Power mode with tripping						
		Set torqu	e/power	r/r.p.m.				
Display	RPM/POWER/TORQUE/JULES in 3 ¹ / ₂ digit red glow LED							
Protection	0	ver/under	voltage	& r.p.m.				
Ergometers Controllers Dimension(inches):								
MEGM001	08X06X06	MEGM050	14X12X1	12				
MEGM003	10X06X06	MEGM100	16X14X1	4				
MEGM005	12X08X08	MEGM200	18X16X1	16				

20X18X18

20X18X18

MEGM300

MEGM500

MEGM-750 20X18X18



mobile ergometer

Three numerals x 1000 after MEGM indicates power of ergometers Electronic controllers with tailor made specifications are also offered. MOTORON SEMICONDUCTORS CORPORATION

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